# A PRECISE GEOIDAL MAP OF THE SOUTHERN PART OF EGYPT, BY COLLOCATION: TOSHKA GEOID

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## ABSTRACT:

This paper presents the final results of computing a 5'x5' grid values of geoidal heights, of the southern part of Egypt that lies between  $(22^{\circ}N \le \phi \le 25^{\circ}N; 28^{\circ}E \le \lambda \le 34^{\circ}E)$ , where the government have begun one of the mega national projects of developmental work, in virgin areas of Egypt's vast deserts, named Toshka project. The ultimate goal was to render a high precise geoid map that serves the newly geodetic activities undertaken in the considered area. In the current investigation, we have exploited all the old and the recent available heterogeneous geodetic data in the same area to compute the required values of geoidal heights by using the Least-Squares Collocation (LSC) technique. The remove-restore procedure was adopted, by the aid of an appropriate high degree global harmonic model, tailored to the local terrestrial data. A digital terrain model for Egypt was also used for the same purpose. The final results of comparing the predicted geoidal heights with the observed ones at certain check points, have shown a rather good external accuracy that reaches 16 cm.

## 1 INTRODUCTION

Recently, the virgin desert area of the southern part of Egypt have seen the beginning of a revolutionary era of agricultural and industrial development, since the Egyptian government have decided to begin one of its national mega projects for development in that area, named Toshka project. This led to the need for accurate maps of different kinds for this long time neglected area. The accuracy required for such maps necessitates, in turn, the knowledge of the accurate and precise geoid at the same area. This is why we have decided to make this study, especially after the relevant data of that area have been available to us. It should be noted that the region under study may be considered as composed of two areas, which were separately investigated by (Abd-Elmotaal, 1998 and Tscherning et. al., 2001). However, in the current study, a locally fitted geopotential model is used as a reference field, besides, a DEM is utilized for smoothing the available data. After the (LSC) prediction, the effects of both removed parts were added to the predicted signals, at the computation points each 5'x5', to get the final geoid values, relative to the WGS-84 ellipsoid. The operation of subtracting and adding the effect of the systematic parts of the data, before and after the prediction process, is usually known in literatures as the Remove-Restore technique The final results were then used to produce two contour maps, representing the geoid and its error standard deviations, for the whole studded area.

#### 2 DATA TYPES, REDUCTION, FILTRATION AND SMOOTHING

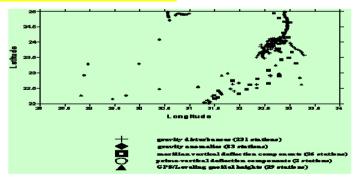


Figure (1): Heterogeneous data distribution in the considered area

#### Long and short wavelength contributions

In the current investigation, we have used a tailored model, denoted as EGM96EGCT, generated by the authors, using the LSC method, and estimated up to degree and order 599, based on the coefficients of the global model EGM96 and all the available terrestrial geodetic data in Egypt. The reliability of this tailored model to recover the long wavelength features of the Egyptian gravity field in an efficient manner has been verified (Amin et al., 2003b). In a previous work by the authors (Amin et al., 2003a), a detailed 5'x5' digital elevation model DEM for Egypt was computed by collocation, based on the available local height data and the global high-resolution topographic harmonic model GTM3A. Using the RTM method, this DEM model has been utilized in the current study for removing the high frequency features.

(unit: mgals)							
<u>Item</u>	Mean	Std. Dev.	RMS	Min.	Max.		
Free air gravity anomaly	4.965	17.857	18.431	-25.688	69.005		
RTM reduced gravity anomaly	11.244	19.136	22.095	<b>-20.911</b>	75.002		
Final (RTM + EGM96EGCT)	4.092	16.591	16.991	<del>-24.632</del>	51.277		
residual gravity anomaly							

Table (2): Statistics of original and residual gravity disturbance data

(unit: mgals)								
Item	Mean	Std. Dev.	RMS	Min.	Max.			
Free air gravity disturbance	-2.159	8.182	8.445	-23.389	18.032			
RTM reduced gravity disturbance	0.597	8.434	8.437	-19.081	22.584			
Final (RTM + EGM96EGCT) residual gravity disturbance	-0.815	6.775	6.810	-19.021	17.858			

Table (3): Statistics of original and residual meridian deflection component data ( $\xi$ )

	(unit: ar	c-seconds)			
<u>Item</u>	Mean	Std. Dev.	$\mathbf{RMS}$	Min.	Max.
<u>E</u>	-0.789	2.351	2.437	-7.021	3.380
RTM reduced ξ	-0.924	2.206	2.353	-6.637	2.588
Final (RTM + EGM96EGCT) residual ξ	-0.243	1.785	1.767	-3.660	3.346

Table (4): Statistics of original and residual prime-vertical deflection component data (η)

(unit. arc-seconds)								
<u>Item</u>	Mean	Std. Dev.	$\mathbf{RMS}$	Min.	Max.			
H	-5.527	1.527	5.632	-6.607	4.448			
RTM reduced η	-5.465	1.575	5.577	-6.578	-4.351			
Final (RTM + EGM96EGCT) residual η	-1.585	1.656	1.971	-2.756	-0.414			

## 3 COMPUTATION TECHNIQUE, PROCEDURES AND RESULTS

### Local covariance function

Since the dominant data type used in this particular work was the gravity disturbance, the computed residual parts  $\delta g_r$  of this element were therefore depicted and utilized to determine this function. Practically, this have been done by evaluating the product sum average of pairs of gravity disturbance signals, relevant to point pairs having spacing  $(\psi - \Delta \psi)/2 \le \psi \le (\psi + \Delta \psi)/2$ .

In order to perform the different steps of calculation by collocation, we must have a covariance function model that represents the local area well. This is usually achieved by fitting the estimated values of the empirical covariance function to a model function in a none-linear iterative least-squares adjustment with three parameters. In this respect, we have used the well-known formula of the anomalous potential covariance function model that reads (Tscherning, 1993),

$$C(P,Q) = C(r, r', \psi)$$

$$= \sum_{n=2}^{N_{\text{max}}} c.\sigma_{\text{neT.model}}^2 \left(\frac{R_b^2}{rr'}\right)^{n+1} P_n(\cos\psi) + \left(\frac{R_b^2}{rr'}\right)^{n+1}$$

(1)

with

Nmax = maximal degree of the removed reference field ( = 599) C = 0.001037  $A = 15.627 \text{ mgal}^2$  $R_B - R = -249.682 \text{ m}$ 

Figure (2) illustrates the input residual gravity disturbance isotropic empirical covariance function, and its associated fitted analytical function. The obtained final values were then used as input for the collocation process.

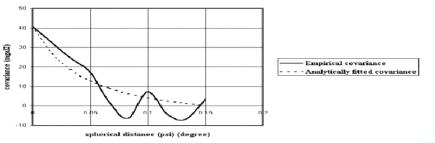


Figure (2): Residual gravity disturbance empirical and fitted covariance functions

#### Least-squares collocation procedures and computations

The vector of the residual geoid undulation  $N_r$  is computed from the vector of observations x from which the GGM and DTM contributions have been computed and removed,

$$N_r = C_{Nx} (C_{xx} + C_{nn})^{-1} x_2,$$

(2)

where  $C_{xx}$  and  $C_{Nx}$  are the auto- and cross- covariance matrices between the observations and the predicted geoid, as evaluated from the computed parameters of the selected analytical model; and  $C_{nn}$  is the error (noise) covariance matrix of the observations. The error covariance matrix of the estimated geoid undulations is given by

$$C_{ee} = C_{NN} - C_{Nx} (C_{xx} + C_{nn})^{-1} C_{xN}$$

(3)

where  $C_{NN}$  is the auto-covariance matrix of N.

## 4 FINAL RESULTS, CONCLUSIONS AND RECOMMENDATIONS

The contributions of both the tailored harmonic model and DEM were then added back (restored) to the residual geoid values predicted at the 5'x5' grid nodes, in order to obtain the respective 5'x5' full spectrum geoid values as well as their error estimates. Table (5) shows the statistics of the predicted geoid. Table (6) shows the accuracy, resulting from the comparison at GPS/Lev. check points, which have not been used as data points. Finally, Figures (3) and (4) show the contour maps of the geoid and its error standard deviations, respectively.

Table (5): Statistics of the residual and full predicted 5'x5' Toshka geoid

(Cinc. meters)								
Item	Mean	Std. Dev.	RMS	Min.	Max.			
Residual N	0.038	0.059	0.071	-0.074	0.390			
Final N	11.036	1.819	11.185	7.489	16.641			
Std. error	0.046	0.003	0.046	0.019	0.047			

Table (6): Statistics of the differences among the observed and predicted geoidal heights

at SI S/Develing check stations (				(Cinc. meco	/	
Item		Mean	Std. Dev.	RMS	Min.	Max.
N(obs.) - N(1)	pred.)	0.017	0.161	0.159	-0.355	0.380

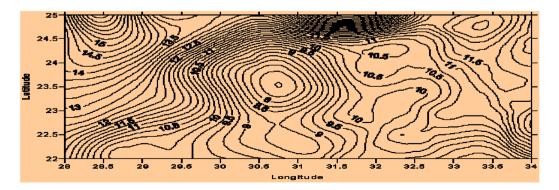


Figure (3): Contour map for the 5'x5' Toshka geoid (Interval: 0.25 m)

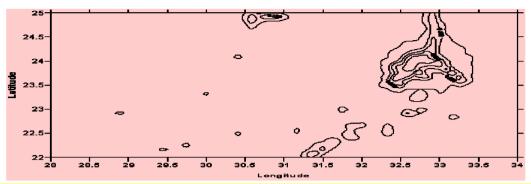


Figure (4): Contour map for the standard errors of the 5'x5' Toshka geoid (Interval: 5 mm)

Therefore, based on the results, the obtained Toshka geoid is highly recommended to be used for any future geodetic computation in the newly developed sector of the southern part of Egypt. It is also recommended to be utilized for densifying leveling networks of lower order through GPS observations, especially in remote areas of the western or eastern desert of that part of Egypt. Consequently, appropriate future planning for rigorous GPS measurements in these areas is highly recommended.

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