

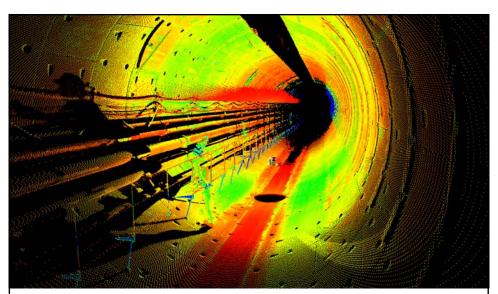
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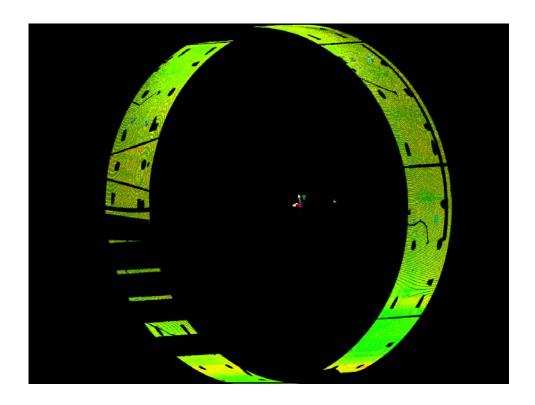


Deformation measurements of newly built tunnels with a Leica HDS 6100 phase-based laser scanner.

'Liefkenshoek rail link' project (Antwerp, Belgium)









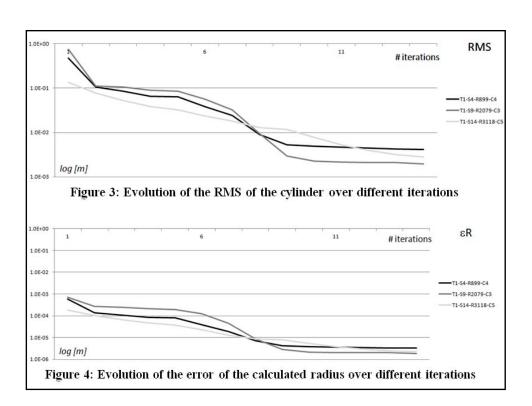
Point set filtering: removal of points not belonging to the tunnel's surface → binary filtering

- Manual: time consuming
- Automatic: assume the local section as a cylinder
  - → implementation of Levenberg-Marquardt algorithm



#### Levenberg-Marquardt algorithm:

- Iterative parameter adjustment and point removal
- Gauss-Newton method (assumption of global non-linearity)
- Steepest descent method (assumption of local linearity)
- For a given point set  $\mathbf{x}$  with  $(\mathbf{x} \in R^3)$ , the parameter estimation of a cylinder will result in a set of parameters  $\mathbf{p}$  with  $\mathbf{p} = (\mathbf{x}, \mathbf{A}, r)$ . Here,  $\mathbf{x}$  is any point on the cylinder axis,  $\mathbf{A}$  is the rotation matrix and  $\mathbf{r}$  is the cylinder radius





Comparison between cross-sections derived from

- manually filtered point cloud
- automatically filtered point cloud

Two-sided t-test to determine whether the difference is statistical significant (95 % level of confidence).



- Levenberg-Marquardt algorithm has proven to be successful for filtering
- Satisfactory results (comparable cross-sections) were obtained
- Further optimization of application to reduce processing time is needed



Thank you!

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